



# **17th IEEE Latin American Robotics Symposium - LARS 2020**

## **8th Brazilian Symposium of Robotics - SBR 2020**

### **Certificate of Participation**

*This is to certify that article 210119 “Visual Predictive Control Scheme for a Mobile Robot Navigating in a Cluttered Environment” by authors Adrien Durand-Petiteville, Viviane Cadenat has been presented at the Latin American Robotics Symposium and Brazilian Symposium on Robotics 2020 that was held in Natal, RN, Brazil, from 9th to 13th of November, 2020.*

**Prof. Dr. Luiz Marcos Garcia Gonçalves - UFRN**

**Prof. Dr. Bruno Marques Ferreira da Silva - UFRN**

**Sponsor:**



**Promotion:**



**Realization:**

