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Certificate of Participation

This is to certify that article 210376 “WaiterBot: Comparison of Fuzzy Logic Approaches for Obstacle Avoidance in Dynamc Unmapped Environments Using a Laser Scanning System (LiDAR)” by authors Jonathan Cerbaro, Dieisson Martinelli, João Fabro, Andre Schneider de Oliveira has been presented at the Latin American Robotics Symposium and Brazilian Symposium on Robotics 2020 that was held in Natal, RN, Brazil, from 9th to 13th of November, 2020.

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