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Certificate of Participation

This is to certify that article 210450 “Fast and Safe Path Planning Method for an Autonomous Smart Walker” by authors Luís Nascimento, Joelson Rocha, Vitor Santos, Diego Pereira, Pablo Alsina, Anselmo Frizera-Neto has been presented at the Latin American Robotics Symposium and Brazilian Symposium on Robotics 2020 that was held in Natal, RN, Brazil, from 9th to 13th of November, 2020.

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